Ros 설치 명령어 모음

sudo sh -c 'echo "deb http://packages.ros.org/ros/ubuntu $(lsb\_release -sc) main" > /etc/apt/sources.list.d/ros-latest.list'

sudo apt-key adv --keyserver 'hkp://keyserver.ubuntu.com:80' --recv-key C1CF6E31E6BADE8868B172B4F42ED6FBAB17C654

sudo apt-get update

sudo apt-get install ros-kinetic-desktop-full

sudo rosdep init

rosdep update

echo "source /opt/ros/kinetic/setup.bash" >> ~/.bashrc

source ~/.bashrc

source /opt/ros/kinetic/setup.bash

sudo apt install python-rosinstall python-rosinstall-generator python-wstool build-essential

**~/.bashrc 파일 넣을 명령어**

alias cw='cd ~/catkin\_ws'

alias cs='cd ~/catkin\_ws/src'

alias cm='cd ~/catkin\_ws && catkin\_make'

source /opt/ros/kinetic/setup.bash

source ~/catkin\_ws/devel/setup.bash

export ROS\_LOCALIP=xxx.xxx.xxx.xxx

export ROS\_MASTER\_URI=http://${ROS\_LOCALIP}:11311